

# Algebraic Topology Problem Set 3

Please hand in questions 2 and 3 on Tuesday 11th March.

## Q1:

In this problem we give an alternative way of understanding the map  $q: S^n \rightarrow \mathbb{R}P^n$ .

Suppose that  $A \in M_{n+1}\mathbb{R}$  and  $A^2 = A$ . Put  $U = \{x \in \mathbb{R}^{n+1} \mid Ax = x\}$  and  $V = \{x \in \mathbb{R}^{n+1} \mid Ax = 0\}$ .

- Prove that  $U$  and  $V$  are vector subspaces of  $\mathbb{R}^{n+1}$ .
- Prove that  $\mathbb{R}^{n+1} = U \oplus V$  (or in other words  $\mathbb{R}^{n+1} = U + V$  and  $U \cap V = \{0\}$ ). [Hint:  $x = Ax + (x - Ax)$ ].
- Now suppose that  $A^T = A$ . Prove that every vector in  $U$  is orthogonal to every vector in  $V$ . [Hint:  $\langle Au, v \rangle = \langle u, A^T v \rangle$ ].
- Put  $k = \dim(U)$ , let  $\{u_1, \dots, u_k\}$  be a basis for  $U$ , and let  $\{u_{k+1}, \dots, u_{n+1}\}$  be a basis for  $V$ , so that  $\{u_1, \dots, u_{n+1}\}$  is a basis for  $\mathbb{R}^{n+1}$ . We can choose these bases to be normalised, so each  $u_i$  is a unit vector. What is  $Au_i$ ? If  $P$  is the matrix whose columns are the vectors  $u_i$ , then what is  $P^{-1}AP$ ?
- What is  $\text{trace}(A)$ ? [Hint: use (d) and the fact that  $\text{trace}(BC) = \text{trace}(CB)$ ]
- Now suppose that  $\text{trace}(A) = 1$ . Prove that  $Au_i = q(u_i)u_i$  for all  $i$  and deduce that  $A = q(u_1)$ .

**Q2:** Define a continuous map  $f: \mathbb{R} \rightarrow \mathbb{R}$  by  $f(x) = \exp(-x^2)$ .

- Sketch the graph of  $f$ .
- Find an open set  $U \subseteq \mathbb{R}$  such that  $f(U)$  is not open.
- Find a closed set  $F \subseteq \mathbb{R}$  such that  $f(F)$  is not closed.
- Find a compact set  $K \subseteq \mathbb{R}$  such that  $f^{-1}(K)$  is not compact.
- Find sets  $A, B \subseteq \mathbb{R}$  such that  $f(A \cap B) \neq f(A) \cap f(B)$ .

## Q3:

- Let  $X$  be a metric space, and let  $U$  and  $V$  be open subsets of  $X$  such that  $X = U \cup V$ . Suppose that  $f: U \rightarrow Y$  and  $g: V \rightarrow Y$  are continuous maps such that  $f(x) = g(x)$  for all  $x \in U \cap V$ . There is then a unique function  $h: X \rightarrow Y$  such that  $h(x) = f(x)$  for  $x \in U$  and  $h(x) = g(x)$  for  $x \in V$ . Prove that  $h$  is continuous.
- Let  $X$  be a metric space, let  $U \subseteq X$  be open and let  $F \subseteq X$  be closed, and suppose that  $X = U \cup F$ . Suppose that  $f: U \rightarrow Y$  and  $g: F \rightarrow Y$  are continuous maps such that  $f(x) = g(x)$  for all  $x \in U \cap F$ , so there is a unique function  $h: X \rightarrow Y$  such that  $h(x) = f(x)$  for  $x \in U$  and  $h(x) = g(x)$  for  $x \in F$ . Give an example to show that  $h$  need not be continuous.

**Q4:** Put  $X = \{A \in M_2\mathbb{R} \mid A^2 = A \text{ and } \text{trace}(A) = 1\}$  (so  $\mathbb{R}P^1 = \{A \in X \mid A = A^T\}$ ). In this problem we prove that  $X \simeq S^1 \times \mathbb{R}$ .

Define  $f: \mathbb{R}^3 \rightarrow M_2\mathbb{R}$  by

$$f(x, y, z) = \frac{1}{2} \begin{pmatrix} 1 + x - yz & y + z + xz \\ y - z + xz & 1 - x + yz \end{pmatrix}.$$

- Calculate  $\text{trace}(f(x, y, z))$  and  $\det(f(x, y, z))$  when  $(x, y, z) \in S^1 \times \mathbb{R}$ .
- The Cayley-Hamilton theorem for  $2 \times 2$  matrices (which you can prove directly for yourself if you wish) says that  $A^2 - \text{trace}(A)A + \det(A)I = 0$ . Using this, show that  $f$  gives a map  $S^1 \times \mathbb{R} \rightarrow X$ .
- Show that

$$f(\cos(2\theta), \sin(2\theta), z) = R_\theta P(z) R_\theta^{-1}$$

$$\text{where } P(z) = \begin{pmatrix} 1 & z \\ 0 & 0 \end{pmatrix} \text{ and } R_\theta = \begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix}.$$

- Show that if  $B \in X$  and  $Be_1 = e_1$  then  $B = P(z)$  for some  $z$ . (Here  $e_1$  is the standard basis vector  $(1, 0)$ ).

- (e) Suppose that  $A \in X$ . Show that there is a unit vector  $u$  such that  $Au = u$ . Show that if  $u = (\cos(\theta), \sin(\theta))$  then  $R_\theta^{-1}AR_\theta = P(z)$  for some  $z$ . Deduce that  $f: S^1 \times \mathbb{R} \rightarrow X$  is surjective.
- (f) Define  $g: M_2\mathbb{R} \rightarrow \mathbb{R}^3$  by

$$g \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \left( \frac{b^2 - c^2 + 2a - 1}{1 + (b - c)^2}, \frac{2(b - a(b - c))}{1 + (b - c)^2}, b - c \right).$$

Check that  $g(f(x, y, z)) = (x, y, z)$ . Deduce that  $f: S^1 \times \mathbb{R} \rightarrow X$  is injective and thus bijective. Deduce in turn that  $f: S^1 \times \mathbb{R} \rightarrow X$  is a homeomorphism.

**Q5:**

Put  $SL_2\mathbb{R} = \{A \in M_2\mathbb{R} \mid \det(A) = 1\}$ . This evidently contains the group  $SO(2)$ , which we have seen is homeomorphic to a circle. Here we will show that  $SL_2\mathbb{R}$  is homeomorphic to  $S^1 \times \mathbb{R}^+ \times \mathbb{R}$  (where  $\mathbb{R}^+ = \{x \in \mathbb{R} \mid x > 0\} = (0, \infty)$ ).

Given  $(x, y) \in S^1$  and  $v \in \mathbb{R}^+$  and  $w \in \mathbb{R}$  we put

$$R(x, y) = \begin{pmatrix} x & -y \\ y & x \end{pmatrix} \in SO(2) \subset SL_2\mathbb{R}$$

$$D(a) = \begin{pmatrix} a & 0 \\ 0 & 1/a \end{pmatrix}$$

$$T(b) = \begin{pmatrix} 1 & b \\ 0 & 1 \end{pmatrix}$$

$$f(x, y, a, b) = R(x, y)D(a)T(b).$$

- (a) Check that all the above matrices lie in  $SL_2\mathbb{R}$ , so we have a continuous map  $f: S^1 \times \mathbb{R}^+ \times \mathbb{R} \rightarrow SL_2\mathbb{R}$ .
- (b) Suppose that  $B \in SL_2\mathbb{R}$  and  $Be_1 = e_1$  (where  $e_1 = (1, 0)$  is the first standard basis vector). Prove that  $B = T(b)$  for some  $b \in \mathbb{R}$ .
- (c) Suppose that  $A \in SL_2\mathbb{R}$ . Put  $u = Ae_1$  and  $a = \|u\|$  and  $v = u/a$ , so  $v \in S^1$ . Prove that  $D(a)^{-1}R(v)^{-1}A = T(b)$  for some  $b \in \mathbb{R}$ .
- (d) Deduce that  $f$  is surjective.
- (e) Define  $g: SL_2\mathbb{R} \rightarrow S^1 \times \mathbb{R}^+$  by  $g(A) = (Ae_1/\|Ae_1\|, \|Ae_1\|)$ . Show that  $g(f(u, a, b)) = (u, a)$ .
- (f) Deduce that if  $f(u, a, b) = f(u', a', b')$  then  $u = u'$  and  $a = a'$ ; then deduce in turn that  $b = b'$  as well. This shows that  $f$  is injective and thus bijective.
- (g) Suppose that  $A_n \rightarrow A$  in  $SL_2\mathbb{R}$ , and put  $f^{-1}(A_n) = (u_n, a_n, b_n)$  and  $f^{-1}(A) = (u, a, b)$ . Using  $g$  show that  $u_n \rightarrow u$  and  $a_n \rightarrow a$ . By considering the matrices  $B_n = D(a_n)^{-1}R(u_n)^{-1}A_n$ , deduce that  $b_n \rightarrow b$ . Now deduce that  $f$  is a homeomorphism.